

# PUBLIC SUBMISSION

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**Comment On:** NSF-2025-OGC-0001-0001  
Request for Information: Development of a 2025 National Artificial Intelligence Research and Development Strategic Plan

**Document:** NSF-2025-OGC-0001-DRAFT-0177  
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## Submitter Information

**Name:** Victoria Webster-Wood

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## General Comment

See attached file(s)

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## Attachments

CRCNS 2025 RFI Neuroscience\_Inspired\_AI

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### Name of Submitter:

Victoria Webster-Wood on behalf of self and collaborators, Roger Quinn, Nick Szorcinski, Gary Marsat, Amir Barati Farimani

### Area Recommended for Investment:

Neuroscience-Inspired Artificial Intelligence for Embodied Robotic Systems

### Overview

Modern artificial intelligence (AI) systems, particularly large neural models (LNMs) such as Transformers, have achieved remarkable success in language processing. However, these models remain underexplored in domains requiring real-time, high-dimensional, and sequential decision-making—such as robotic control in complex environments. Moreover, current LNMs are computationally intensive, energy-inefficient, and lack the adaptability, long-term learning, and behavioral flexibility observed in biological systems. This call seeks bold, interdisciplinary research proposals that draw inspiration from neuroscience to overcome these limitations. We invite teams to explore how principles from biological nervous systems—such as modularity, developmental plasticity, predictive feedback, and embodiment—can be integrated into AI architectures to enable energy-efficient, adaptive, and resilient robotic intelligence.

### Research Focus Areas

Proposals should address one or more of the following themes:

- **Heterogeneous Neural Architectures:** Incorporating brain-like modularity and specialization into LNMs to improve learning efficiency and generalization.
- **Developmental Mechanisms:** Modeling neural growth, apoptosis, and synaptic plasticity to reduce training costs and enhance adaptability.
- **Temporal Dynamics:** Embedding multi-timescale dynamics inspired by biological neurons to support long-horizon planning and control.
- **Sensorimotor Prediction:** Designing brain-inspired circuits for sparse encoding and real-time feedback in robotic systems.
- **Embodied Intelligence:** Co-designing physical robot platforms and AI control systems to study the interaction between body mechanics, sensing, and cognition.

## Expected Outcomes

Proposals should aim to achieve the following outcomes:

- Novel AI architectures that integrate neuroscience principles
- Demonstrated improvements in energy efficiency, learning speed, and task performance
- Embodied robotic systems capable of complex and adaptive behavior
- Open-source tools, benchmarks, and datasets to support the broader research community

## Proposal Requirements

Proposals must include:

- Multidisciplinary teams with expertise in neuroscience, AI/ML, and robotics
- Clear experimental validation plans using physical robotic platforms
- Quantitative benchmarks comparing proposed methods to state-of-the-art LNMs